

# User Manual

Item No. 8065 | Ages 8+

R O B O R E P T I L E<sup>™</sup>  
A F U S I O N O F T E C H N O L O G Y A N D P E R S O N A L I T Y

Congratulations on purchasing your new Roboreptile.

Be sure to read this manual carefully for a complete understanding of the many features of your new Roboreptile.



Remote Controller      Hood Accessory

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## Battery requirements

Your remote controller is powered by 3 x "AA" size batteries (not included).

Your Roboreptile is powered by 6 x "AA" size batteries (not included).

## Battery installation

- 1 Before installing or changing batteries, ensure the Roboreptile's ON/OFF button is in the OFF position.
- 2 Remove the battery compartment covers using a Phillips or crosshead screwdriver (not included).
- 3 Insert batteries (not included) into the Roboreptile and controller as shown in the diagrams.
- 4 Replace the battery compartment covers and the screws.
- 5 Press the ON/OFF button to the ON position.

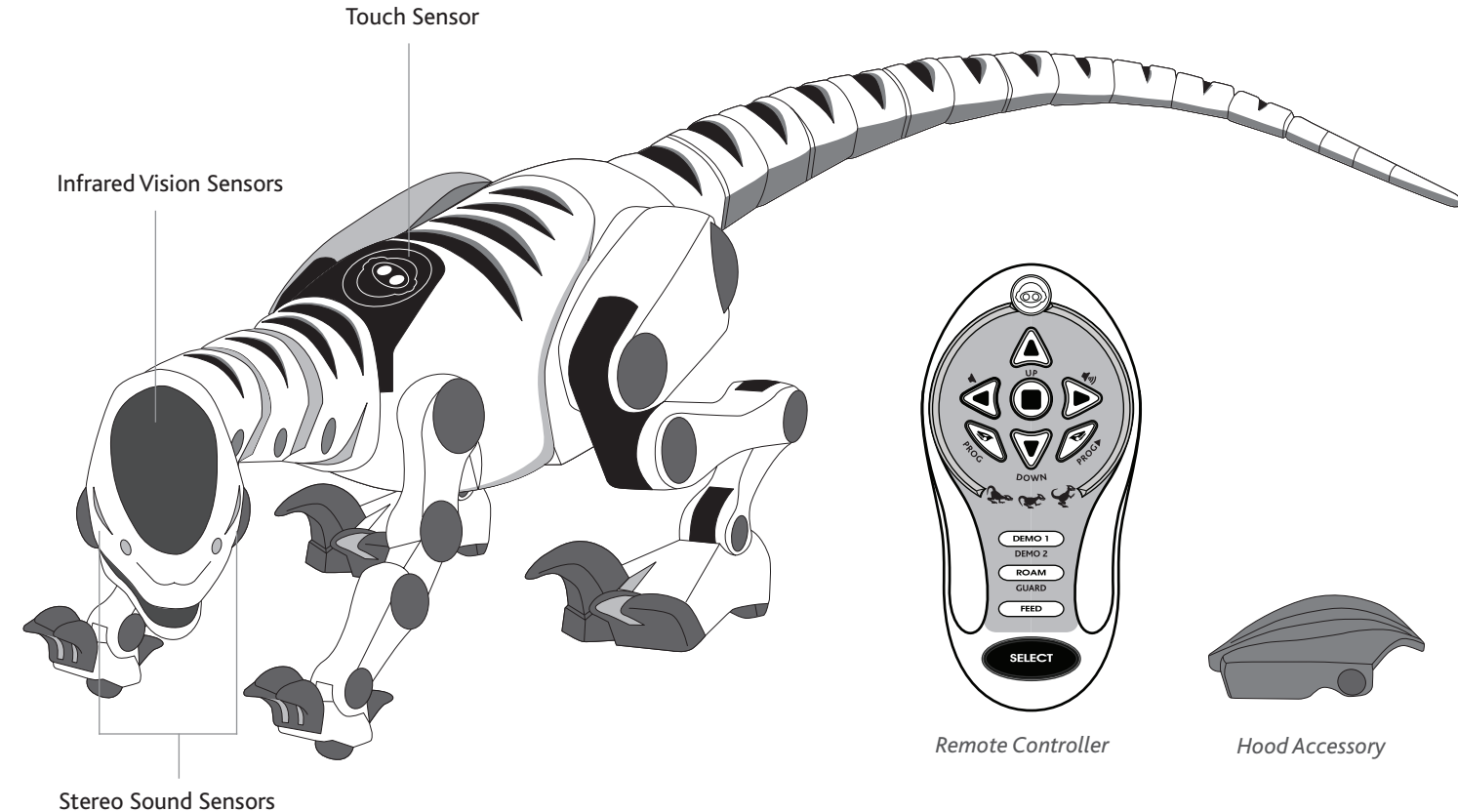
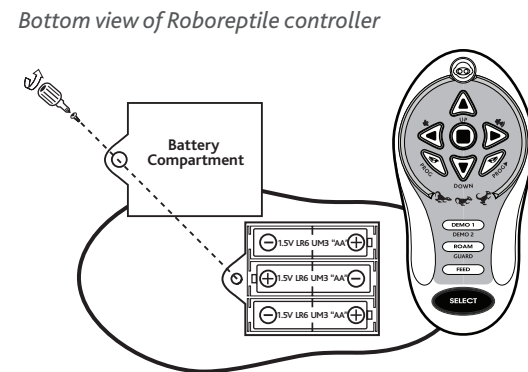
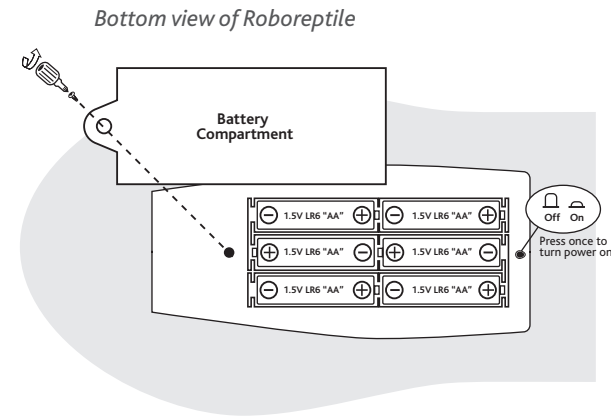
## Powering ON

Roboreptile will perform a start-up routine which cannot be interrupted and will then wait for interaction.

If no interaction is given for about 30 seconds, Roboreptile will enter Free Roam Mode.

### Attention: Important Battery Information

- Use only fresh batteries of the required size and recommended type
- Do not mix old and new batteries, different types of batteries [standard (Carbon-Zinc), Alkaline rechargeable] or rechargeable batteries of different capacities
- Remove rechargeable batteries from the toy before recharging them
- Rechargeable batteries are only to be charged under adult supervision
- Please respect the correct polarity, (+) and (-)
- Do not try to recharge non-rechargeable batteries
- Do not throw batteries into the fire
- Replace all batteries of the same type/brand at the same time
- The supply terminals are not to be short-circuited
- Remove exhausted batteries from the toy
- Batteries should be replaced by adults because of small parts
- Remove batteries if the toy is not going to be played with for some time
- The packaging should be kept since it contains important information



The Remote Controller has 3 layers

































Press the Select Button to cycle through the layers.

The light stays lit (layer active) for about 30 seconds after the last button press and then returns to 'layer1'.

To see these controls outlined in more detail:

- Controller Layer 1 p.12
- Controller Layer 2 p.13
- Controller Layer 3 p.14

Roboreptile responds to remote control commands more easily when you are in front of him. He will not see as well if the controller is behind him.

Layer 1	Layer 2 Press  x1	Layer 3 Press  x2
No light	Red light	Green animated light
Forward 	Up on back legs 	Jump 
Backward 	Down on all fours 	Sweep 
Left 	Volume up 	Tail strike left 
Right 	Volume down 	Tail strike right 
Stop 	Stop 	Stop 
Head left 	Program mode 	Attack 
Head right 	Program play 	Shake 
Demo 1 	Demo 2 	Dizzy 
Roam 	Guard mode 	Bite 
Feed 	Feed 	Feed 

Roboreptile starts in Direct Control Mode and is in this state whenever he is waiting for or performing a controller command.

Roboreptile enters Free Roam if his Touch Sensor is pressed, after reacting to sound, if the Free Roam button is pressed, after reacting to infrared vision, after feeding, after the hood is removed, or if he is left standing for 30 seconds.

While in Free Roam mode, Roboreptile will avoid obstacles using his Infrared Vision System. Occasionally he will stop moving and listen for sharp, loud sounds using his Sonic Sensors. During this time he will also react to IR vision or to a touch on the sensor.

Roboreptile's response to environmental stimuli depends on the mood he is in - Hungry Mood or Full Mood.

**Hungry**  
This is Roboreptile's default mood. He is always hungry, aggressive and active while in this mood.

**Satisfied**  
This is after he has been fed (see p.7). He is lethargic and slow. To leave Satisfied Mood, leave him for 60 seconds or press any controller button.

**Hooded**  
With the hood on, Roboreptile is in Hooded Mood. Roboreptile's vision and sound sensors are inactive in this mood. To activate Roboreptile, remove his hood and he will be in Hungry Mood. (See p.8)

If left in Free Roam Mode for about 5 minutes without any user interaction, Roboreptile will power down and the only way to power him back up is to turn him OFF and then ON again.

## HOODED AND SLEEP MODE

It is possible to calm Roboreptile down by Hooding him. By placing a hood over his head, Roboreptile will be unable to react to his surroundings as you have covered his Vision and Sonic sensors - this is Hooded Mood.

Roboreptile can be difficult to hood when he is in Hungry Mood as he is very aggressive. It is easier to put the Hood accessory onto Roboreptile after he has eaten (see Feeding - p.7), as he will be calmer and less likely to shake the hood off.

If Roboreptile succeeds in shaking the hood off before he calms down, he will be really angry!

### Hooded - Subdued

With the hood on, Roboreptile is now subdued but if you take his hood off, he will wake up angrily. During this time he will periodically omit a calm breath sound.

### Hooded - Sleep Mode

After about 40 seconds Roboreptile will fall asleep. If you take his hood off now he will wake up slowly. He will not make the breathing sound during this time.

### Power down

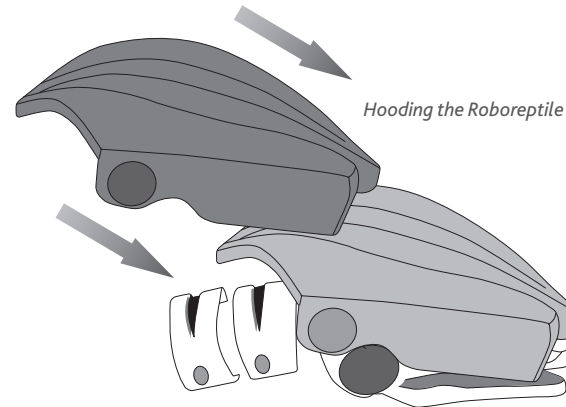
After sleeping for approximately 10 minutes, Roboreptile will power down to save his batteries. The only way to wake him up now is by turning him OFF and then ON again.

By listening to Roboreptile's breathing you can tell whether he is subdued or asleep. Roboreptile will still respond to his touch sensor until he has gone into sleep mode.

If he succeeds in shaking off the hood before calming down, it will be a different reaction than when the user removes it.

It is difficult to put the hood onto Roboreptile's head if he has not been fed. Slide the Hood over Roboreptile's head from the back to the front. Do not force the Hood onto its head from directly above or from the front.

**NOTE**  
Any object that can cover all the sensors in Roboreptile's head can be used in place of the Hood. Turning off the lights will have the same reaction.



## FEEDING YOUR ROBOREPTILE

Roboreptile can be fed to calm him down. To feed Roboreptile, PRESS AND HOLD the Feed button. He will not react to the feed signal while hooded.

### Tracking

Pressing the feed button will make Roboreptile sit up and track the controller signal left or right with his head. (This will interrupt whatever mode Roboreptile is in).

If the signal goes too far left or right, Roboreptile will follow the controller by turning his body left or right with his legs. It is possible to tease Roboreptile if you keep making him turn in either direction like this while tracking the food.

### Chasing

By holding the controller still for about 4 seconds, Roboreptile will get a bearing on the food source position and go into chase mode.

He will run towards the controller, turning left or right as necessary. (He won't know when he has reached the controller).

If he chases the food for about 30 seconds he will get annoyed.

### Feeding

To make Roboreptile eat, release the feed button.  
To instantly feed Roboreptile, press and quickly release the Feed button.

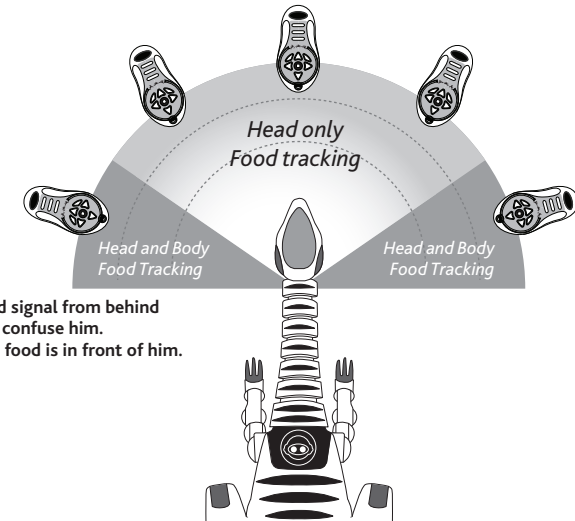
### Satisfied Mood

After he has eaten his mood will change to 'Satisfied Mood'. This will last for 60 seconds (not including interruptions) before he goes back into Hungry Mood.

Roboreptile will track, run and chase his food signal when in Satisfied Mood but he will not eat.

### Signal lost

If the signal is lost he will wander off.



**NOTE**  
Sending the Feed signal from behind Roboreptile will confuse him. He will think his food is in front of him.

Roboreptile has Infrared Vision Sensors that enable him to detect movement and avoid obstacles in his path. The sensors react best to movement in the area just in front of his nose.

Roboreptile's Vision Sensors will react when moving or stationary, but he is unable to see anything when hooded.

## Moving – Obstacle Avoidance

While moving, his reactions are called Obstacle Avoidance and will be the same whether he is in Hungry or Satisfied Mood. Roboreptile uses his vision sensors to avoid obstacles while wandering around.

While walking he is not able to detect movement so he will react to any object (including the user) that enters his field of vision as if it is an obstacle, whether it is moving or stationary.

Press the stop button or wait for him to stop moving before trying to interact with his Vision Sensors.

## Stationary

He will react differently when stationary, to an object entering his field of vision. When he first sees an object he will jump up onto his back legs. He will track the movement of an object left and right.

## Tracking for too long

If Roboreptile tracks an object for too long he will become bored.

## Object lost

If the object Roboreptile is tracking is lost, he can sometimes find it again. If the object has been lost for too long he will walk away.

## Dizzy

Moving the object that Roboreptile is tracking from side to side, and making him turn again and again can make him a little dizzy.

## Pounce

If the object Roboreptile is tracking becomes stationary for about 3 seconds, he will move towards it depending on his mood.

When in Hungry Mood he will jump and lunge for the object.

In Satisfied Mood, Roboreptile is lethargic and will still lunge but with a little less vigor.

Roboreptile will return to Free Roam after all visual interaction ceases.

## IMPORTANT

Roboreptile's Infrared Vision System is based on reflection. This means that he can see highly reflective surfaces like white walls or mirrors more easily and at greater distances. When hooded Roboreptile does not have Infrared capabilities; his vision system is off.

Roboreptile is equipped with a Touch Sensor, which allows him to respond to human interaction.

The Touch Sensor is located on Roboreptile's back, at the base of his neck. He doesn't like his touch sensor being pressed unless he is in Hooded Mood.

Roboreptile can easily be put into Free Roam without the use of the remote controller by pressing the Touch Sensor. Roboreptile will perform a short animation and enter Free Roam.

Obstacle avoidance, turning, and walking backwards will disable the Touch Sensor to allow Roboreptile to safely complete his move.

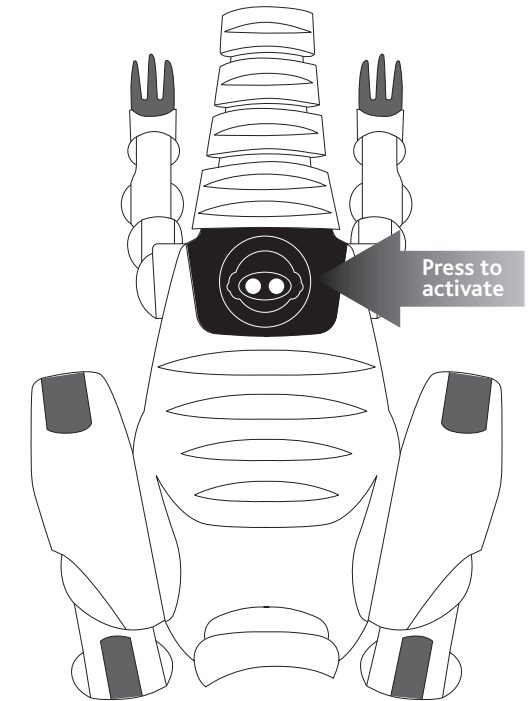
## Hooded Mood

Roboreptile likes his touch sensor being pressed in Hooded Mood. Single or double pat for different reactions.

## NOTE

The Touch Sensor becomes inactive when in Program Mode.

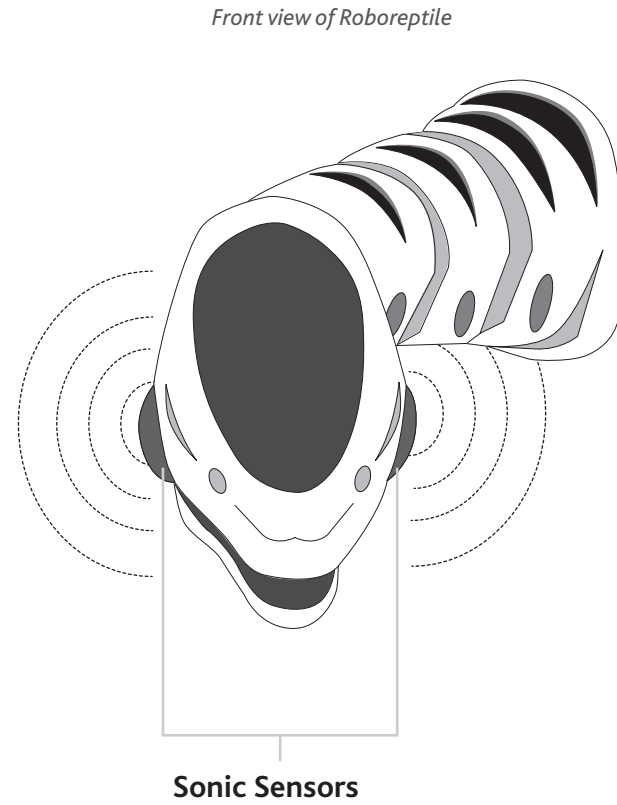
Top view of Roboreptile



Roboreptile has Sonic Sensors located on either side of his head, just behind the jaw. This enables him to detect sharp, loud sounds (like a clap) to his left, right, and directly ahead.

When he hears a sound he will run towards it.

Roboreptile listens when he is not moving, not wearing his hood, and when he isn't in Program Mode. When he is performing a movement or animation his Sonic Sensors are turned OFF.



## Walk

Cycle continuously through 'Forward' (Layer 1) to alter Roboreptile's gaits.

Walk 1 - 4 legs	Fast
Walk 2 - 4 legs	Slow
Walk 3 - 2 legs	Big step
Walk 4 - 2 legs	Small step

To cycle through each walk, the Forward button must be pressed when Roboreptile is still walking, otherwise he will start from Walk 1.

## Jump

Cycle between 2 or 4 legged jumping by pressing Forward in Layer 3. The initial jump style depends on whether Roboreptile is on 2 or 4 legs.

To cycle between the two styles, Roboreptile must be performing a jump when the Forward button is pressed again.

## Turning

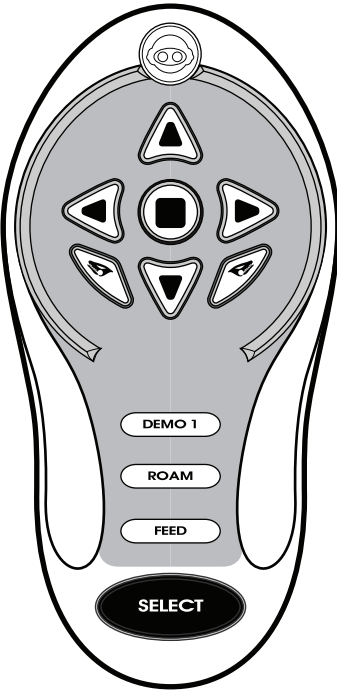
Pressing left or right will make Roboreptile perform a turn on the spot in that direction as you face him. Press the same direction button again during the turn and Roboreptile will start a walking turn.

Pressing the same button will cycle between these two turns.











Walking forward, backwards, or turning lasts for 30 seconds not including obstacle avoidance.

**NOTE**  
Pressing turn will interrupt a walk.

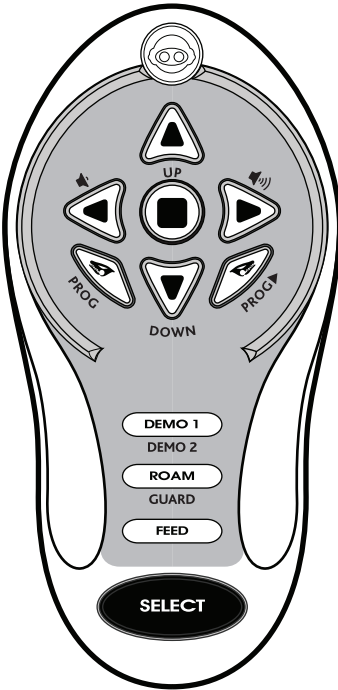














NO LIGHT

Stop		To stop Roboreptile from performing his current action press Stop.
Forward		Press forward to cycle through Roboreptile's four walking gaits. See Walk on p.11
Backward		Press to make Roboreptile move backward.
Left		Press to make Roboreptile perform a stationary turn, press again while he is moving to perform a walk turn.
Right		Press to make Roboreptile perform a stationary turn, press again while he is moving to perform a walk turn.
Head left		Press head left and Roboreptile will look left then back to the front.
Head right		Press head right and Roboreptile will look right then back to the front.
Demo		Press demo to make Roboreptile perform a preprogrammed demonstration of movement and animations.
Roam		To put Roboreptile into Free Roam from Direct Control Mode press Roam.
Feed		Press and hold Feed for Roboreptile feeding interaction (see p.7)

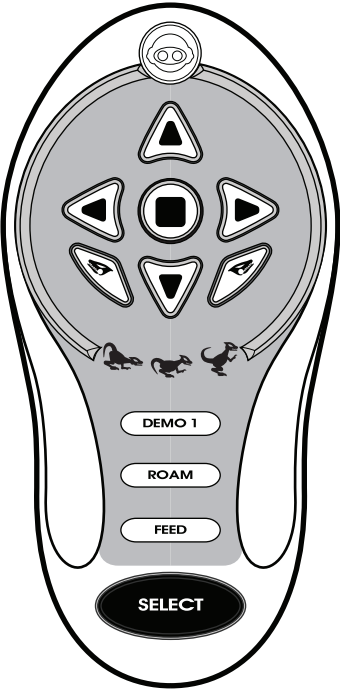
NOTE  
Control Roboreptile as if he is your reflection in a mirror.  
Command example: Press Left and he will move to his Right. Press Right and he will move to his Left.













RED LIGHT

Stop		To Stop Roboreptile from performing his current action press Stop.
Body Up		Press for body up. (Button will do nothing if already in this position).
Body Down		Press for body down. (Button will do nothing if already in this position).
Volume Down		Press to turn the volume down. This will also perform a Stop function.
Volume Up		Press to turn the volume up. This will also perform a Stop function.
Program Mode		Press to enter Program Mode. (see p.15)
Program Play		Press to make Roboreptile play the program stored in his memory. If there is no program stored, he will perform a 'stop'. (see p.15)
Demo 2		Press to make Roboreptile perform a preprogrammed demonstration of animations.
Guard Mode		Press to put Roboreptile into Guard Mode. (see p.16)
Feed		Press and hold Feed for Roboreptile feeding interaction (see p.7)





GREEN ANIMATED LIGHT		
Stop		To stop Roboreptile from performing his current action press Stop.
Forward		Press to make Roboreptile perform jumps. Press again to toggle between 2 styles. See Jump on p.11
Sweep		Press to make Roboreptile perform a sweep.
Left Tail Strike		Press to make Roboreptile perform a left tail strike.
Right Tail Strike		Press to make Roboreptile perform a right tail strike.
Attack		Press to make Roboreptile attack.
Shake		Press to make Roboreptile shake.
Dizzy		Press to make Roboreptile dizzy.
Bite		Press to make Roboreptile bite.
Feed		Press and hold Feed for Roboreptile feeding interaction (see p.7)

A 20-step program can be made using the Direction and Animation buttons.

To ENTER Program Mode press the Program Button. Roboreptile will get up on his back legs and will not move once in Program Mode.

Clearing the Program

**IMPORTANT**  
By entering Program Mode, any programs will be immediately cleared.

Pressing Program Play immediately after entering Program Mode will leave the program clear, as will leaving Roboreptile without entering any program steps.

Programming your Roboreptile

Choose a combination of controller commands from all three layers of the controller to form a program.

There are 20 steps in each program. When a step is successfully entered, a confirmation will be sounded. When Roboreptile is unable to perform a step, a denial will be sounded.

Roboreptile cannot be programmed with the following steps:

- Demo Modes
- Guard Mode
- Volume Control
- Feed
- Stop

Exiting Program mode

To exit Program Mode immediately, press Program Play. Roboreptile will perform a program if one is stored.

To exit Program Mode, the user can leave Roboreptile for approximately 30 seconds

Without inputting any commands, Roboreptile will enter Free Roam Mode after 30 seconds. If commands have been inputted, Roboreptile will perform the routine.

**NOTE**  
Pressing STOP will be considered as a command input and will not exit Roboreptile from Program Mode. Stop does not register as a programmable command in Program Mode.

Playing the Program

The user can replay the program at any time by pressing the Program Play button.

**NOTES**  
Guard Mode, Volume control and Demo Modes will not register while Roboreptile is in Program Mode and cannot be entered as a step in a program.

Pressing the Feed button will not register as a step in the programming of Roboreptile, but will interrupt Program Mode. Roboreptile will start his Feed routine.

The program memory is cleared when Roboreptile is turned off.

Roboreptile's volume can be adjusted using the Volume Control function. When he is powered ON his default volume setting is Full.

Volume Up  In layer 2

Volume Down  In layer 2

There are three volume settings

1  High

2 Low

3  Mute

Altering the volume when Roboreptile is performing a function will cause the function to stop.

Put Roboreptile into Guard Mode to watch over the area immediately around him.

Guard Mode  In layer2

To exit Guard Mode press ANY button.

He will get up on his back legs and become stationary. He will then use his Infrared Vision Sensors and Sonic Sound Sensors to guard the area immediately around him.

If he hears a sound or sees movement he will either

- A** perform a default animation
- B** perform a user programmed routine (if one is programmed)

After about 20 minutes he will power down.

**CAUTION**  
Do not put Roboreptile near the edge of a table since he could fall off when becoming animated.

Control Roboreptile as if he is your reflection in a mirror.

## Command example

Press Left and he will move to his Right.  
Press Right and he will move to his Left.

Roboreptile responds to remote control commands more easily when you are in front of him. He will not see as well if the controller is behind him.

**Please Note**  
Infrared functions can be affected by bright sunlight, flourescent and electronically dimmed lighting.

Upon activation Roboreptile will be sensitive to vision and touch.  
When he has stopped moving he will be sensitive to sound.

Upon activation Roboreptile will become animated.

Do not stand him at the edge of a table or stairs.

In direct control mode, when stationary, Roboreptile will wait 30 seconds (without being triggered by anything) before going into Free Roam.

If the ambient light level is too low, Roboreptile will think his hood has been put on.

When commanded to walk forward, backward, or turn it will last for about 30 seconds. This time will be increased by obstacle avoidance.

#### Caution

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

#### NOTE

This equipment has been tested and found to comply with the limits for a class B digital device, pursuant to part 15 of the FCC rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications.

However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try and correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna
- increase the separation between the equipment and receiver
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected
- Consult the dealer or experienced radio/TV technician for help

We recommend that you retain our address for future reference.

Product and colors may vary. Packaging printed in China.

This product is not suitable for children under 3 years because of small parts - choking hazard.

MADE IN CHINA

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